Universidad
Carlos III de Madrid

| COURSE TITLE: MECHANICS AND RELATIVITY |  |  |
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| BACHELOR IN ENINEERING PHYSICS | YEAR: $\mathbf{2}^{\text {nd }}$ | SEMESTER: $1^{\text {ST }}$ |


| COURSE SCHEDULE |  |  |  |  |  |  |  |  |  |
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| $\begin{gathered} \text { WEE } \\ \text { K } \end{gathered}$ | $\begin{gathered} \text { SE- } \\ \text { SSIO } \\ \mathrm{N} \end{gathered}$ | DESCRIPTION OF THE CONTENTS | $\begin{aligned} & \text { GROUP } \\ & \text { (Tick } \text { ) } \\ & \hline \end{aligned}$ |  | Indicate if a space different from the classroom is required (laboratory, computer classroom, etc) | Indicate YES/NO if It is a session with two teachers | STUDENT'S WEEKLY SCHEDULE |  |  |
|  |  |  | $\begin{aligned} & \text { Lectur } \\ & \text { e } \\ & \text { Class } \end{aligned}$ | $\begin{aligned} & \text { Practi } \\ & \text { cal } \\ & \text { Class } \end{aligned}$ |  |  | DESCRIPTION | CLASS HOURS | HOMEWO RK HOURS Máximum 7 H |
| 1 | 1 | 1. Introduction to Analytical Mechanics <br> - Introduction <br> - Generalized Coordinates <br> - Systems with Constraints <br> - Kinetic Energy and Generalized Momenta <br> * Generalized Velocity <br> * Kinetic Energy <br> * Generalized Momenta <br> - Virtual and Real Displacements <br> - Virtual Work. Generalized Forces <br> * Virtual work <br> * Generalized Forcs <br> * Virtual Work and Forces of Constraint | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |
| 1 | 2 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| 2 | 3 | 1 (cont.) | X |  |  |  | - Reading of proposed topics | 1,66 | 5 |



|  |  | - Fields of Application of the Hamiltonian Mechanics <br> - The Hamilton's Principle. Principle of Least Action |  |  |  |  |  |  |  |
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| 4 | 8 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| ${ }^{5}$ | 9 | 4 Analytical Statics <br> - The Principle of Virtual Work <br> - D'Alembert's Principle | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |
| 5 | 10 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| ${ }^{6}$ | 11 | 5 Introduction to the Rigid Body <br> - Definition of the Rigid Body. Degrees of Freedom <br> - General Motion of a Rigid Body in Space. Chasles Theorem <br> - Angular Velocity of Rotation of a Rigid Body <br> - Kinetic Energy. Köning's Theorem | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |
| 6 | 12 | - Written test exam (*) |  | X |  |  | - Written test exam <br> - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| 7 | 13 | 6. The Inertia Tensor <br> - Rotational Kinetic Energy. Definition of the Inertia Tensor <br> - Angular Momentum with respect to a Point <br> * Angular Momentum <br> * Relation between the Angular Momentum and the Rotational Kinetic Energy <br> - Planar Motion <br> - Properties of the Inertia Tensor <br> - Principal Axes of Inertia <br> * Principal Axes and Principal Moments of Inertia <br> * Procedure to determine the Principal Axes and Moments | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |


|  |  | * Principal Axes and Properties of Symmetry <br> - The Ellipsoid of Inertia |  |  |  |  |  |  |  |
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| 7 | 14 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| 8 | 15 | 7 Equations of Motion of a Rigid Body. Applications <br> - Eulerian Angles <br> * Translational and Rotational Coordinates. Eulerian Angles <br> * Angular Velocity of Rotation as a function of the Eulerian Angles <br> - Equations of Motion <br> - Euler's Equations <br> - Gyroscopic Motion | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1.66 | 5 |
| 8 | 16 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1.66 |  |
| 9 | 17 | 8 Oscillations <br> - Introduction <br> - Formulation of the Problem <br> - The Eigenvalue Equation. Normal Modes and Frequencies <br> - Normal Coordinates <br> - Summary of the Method | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |
| 9 | 18 | - Written test exam (*) |  | X |  |  | - Written test exam <br> - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and debates | 1,66 |  |
| 10 | 19 | 8 (cont.) | X |  |  |  | - Reading of proposed topics <br> - Work on the subject, including bibliographic research | 1,66 | 5 |
| 10 | 20 |  |  | X |  |  | - Solution of proposed exercises <br> - Presentation of short proposed works <br> - Participation in discussions and Debates | 1,66 |  |



(*) Test dates are tentative.
(**) Laboratory session dates are tentative.

