

COURSE: Mobile Robots

STUDY: Master in Robotics and Automation

Year: 1st

Semester: 2nd

| WEEKLY PLANNING OF THE COURSE | | | | | | | | | | | |
|-------------------------------|---------|---|-------------------------|-------|---|--|--|----------------|--|--|--|
| WEEK | SESSION | DESCRIPTION OF THE CONTENT OF THE SESSION | GROUP (Cross with X) | | Indicate if it is in a special room (computer | Indicate if it is or not a session | WEEKLY EFFORT OF THE STUDENT | | | | |
| | | | BIG | SMALL | room, audiovisual room, etc.) | with 2 professors | DESCRIPTION | CLASS HOURS | INDIVIDUAL WORK (Max. 7h /week) | | |
| 1 | 1 | Introduction to the course Introduction to mobile robots. Locomotion systems. Representation of the environment systems. | | х | | No | Lecture on the topic. Individual study of the topic. | 2 | 2 | | |
| 2 | 2 | Geometric navigation. Geometric maps. Location and relocation of mobile robots. SLAM. | | х | | No | Lecture on the topic. Individual study of the topic. | 2 | 2 | | |
| 3 | 3 | Lab: Robotic algorithms. | | Х | | No | Software review. | 2 | 2 | | |
| 4 | 4 | Topological Navigation of mobile robots. Topological maps. Generation of topological maps. Navigation. Location and relocation. | | х | | No | Lecture on the topic. Individual study of the topic. | 2 | 2 | | |
| 5 | 5 | Semantic Navigation. Semantic Modeling. Planning and semantic inference. | | Х | | No | Lecture on the topic. Individual study of the topic. | 2 | 2 | | |
| 6 | 6 | Navigation in outdoor environment. Terrain | | Х | | No | Lecture on the topic. | 2 | 2 | | |

| | | modeling. Crossable and non-crossable areas. Planning in outdoor environment. | | | Individual study of the topic. | | |
|------|-----|---|---|----|--|----|----|
| 7 | 7 | Hardware of mobile robots. Building components of a mobile robot. | х | No | Individual study of the topic. | 2 | 2 |
| 8 | 8 | Lab: Hardware of mobile robots. Building components of a mobile robot. | х | No | Preparation of the lab contents. | 2 | 2 |
| 9 | 9 | Software de mobile robots | Х | No | Individual study of the topic. | 2 | 2 |
| 10 | 10 | Lab: Software de mobile robots | Х | No | Preparation of the lab contents. | 2 | 2 |
| 11 | 11 | Lab: Software de mobile robots | Х | No | Preparation of the lab contents. | 2 | 2 |
| 12 | 12 | Lab: Software de mobile robots | Х | No | Preparation of the lab contents. | 2 | 2 |
| 13 | 13 | Presentation of works. | х | No | Preparation of the presentations of the works. | 2 | 30 |
| 14 | 14 | Presentation of works. | x | No | Preparation of the presentations of the works. | 2 | 30 |
| | | | | | Subtotal 1 | 28 | 94 |
| | 112 | | | | | | |
| 15 | | Recovery classes, tutoring, home-work delivery, etc. | | | | 10 | |
| 16 | | | | | | | |
| 17 | | Preparation of evaluation, and evaluation | | | | 4 | 24 |
| 18 | | | | | | | |
| | 4 | 24 | | | | | |
| | 38 | | | | | | |
| тота | 150 | | | | | | |