



<b>COURSE: MATHEMATICS FOR DATA ANALYSIS</b>		
<b>MASTER IN BIG DATA ANALYTICS</b>	<b>YEAR: 1</b>	<b>TERM: 1</b>

WEEKLY PLANNING							
WEEK	DESCRIPTION	TYPE			NOTES	HOURS	
		LECTURE	PROBLEMS	EXAM		CLASS	WEEKLY TOTAL
1	<ul style="list-style-type: none"> <li>• <b>CHAPTER 1: LINEAR SYSTEMS</b> <ul style="list-style-type: none"> <li>· Number sets</li> <li>· Fundamental Theorem of Algebra</li> <li>· Introduction to Linear Equations</li> <li>· Geometrical Interpretation</li> <li>· Existence and Uniqueness</li> <li>· Matrix Notation</li> <li>· Gaussian Elimination</li> <li>· Row Equivalence and Echelon Forms</li> <li>· Solving Linear Systems</li> <li>· Homogeneous Systems</li> <li>· Simultaneous Solving</li> <li>· Linear Systems with parameters</li> </ul> </li> <li>• <b>CHAPTER 2: VECTORS</b> <ul style="list-style-type: none"> <li>· Vectors</li> </ul> </li> </ul>	X				3	6
2	<ul style="list-style-type: none"> <li>• <b>CHAPTER 2: VECTORS</b> <ul style="list-style-type: none"> <li>· Linear Combinations</li> <li>· Subspace Spanned by Vectors</li> <li>· Linear Subspace</li> <li>· Column and Row Spaces</li> <li>· The Matrix Equation <math>Ax=b</math></li> <li>· Null Space</li> <li>· Revisiting Linear Systems</li> <li>· Linear Independence</li> <li>· Basis for a Linear Subspace</li> <li>· Dimension of a Linear Subspace</li> <li>· Basis for Col A, Row A and Nul A</li> <li>· Rank of a Matrix</li> </ul> </li> </ul>	X				3	6
3	<ul style="list-style-type: none"> <li>• <b>CHAPTER 2: VECTORS</b> <ul style="list-style-type: none"> <li>· Coordinate Systems</li> <li>· Introduction to Linear Transformations</li> </ul> </li> <li>• <b>CHAPTER 3: MATRICES</b> <ul style="list-style-type: none"> <li>· Matrix Operations</li> <li>· Inverse of a Matrix</li> <li>· The LU factorization</li> <li>· Partitioned Matrices</li> <li>· Determinants</li> </ul> </li> </ul>	X				3	6
4	<ul style="list-style-type: none"> <li>• <b>CHAPTER 3: MATRICES</b> <ul style="list-style-type: none"> <li>· Determinants</li> </ul> </li> <li>• <b>CHAPTER 4: DIAGONALIZATION</b> <ul style="list-style-type: none"> <li>· Eigenvalues &amp; Eigenvectors</li> <li>· Diagonalization</li> </ul> </li> </ul>	X				3	6
5	<ul style="list-style-type: none"> <li>• <b>CHAPTER 4: DIAGONALIZATION</b> <ul style="list-style-type: none"> <li>· Change of Basis</li> <li>· Transformations between Linear Subspaces</li> <li>· Markov Processes</li> </ul> </li> <li>• <b>CHAPTER 5: ORTHOGONALITY</b> <ul style="list-style-type: none"> <li>· Dot Product and Modulus</li> <li>· Orthogonal Sets</li> <li>· Orthogonal Matrices</li> <li>· Orthogonal Complement</li> <li>· Orthogonal Projection</li> </ul> </li> </ul>	X				3	6
6	<ul style="list-style-type: none"> <li>• <b>CHAPTER 5: ORTHOGONALITY</b> <ul style="list-style-type: none"> <li>· The Gram-Schmidt Process</li> <li>· The QR factorization</li> <li>· Least-Squares Problems</li> <li>· Linear Regressions</li> <li>· Multiple Regressions</li> </ul> </li> <li>• <b>CHAPTER 6: SYMMETRIC MATRICES</b> <ul style="list-style-type: none"> <li>· Diagonalization of Symmetric Matrices</li> <li>· Quadratic Forms</li> <li>· Singular Value Decomposition</li> <li>· Reduced SVD</li> </ul> </li> </ul>	X				3	6
7	<ul style="list-style-type: none"> <li>• <b>CHAPTER 6: SYMMETRIC MATRICES</b> <ul style="list-style-type: none"> <li>· Pseudoinverse of a Matrix</li> <li>· Karhunen-Loève Expansion</li> <li>· Condition Number</li> <li>· Orthogonal Least-Squares</li> <li>· Principal Component Analysis</li> </ul> </li> </ul>	X				3	6
8	<b>EXAM</b>			X		3	3
	<b>Exam Preparation and Tutorials</b>						30
<b>TOTAL HOURS:</b>							<b>75</b>