



<b>COURSE: : NUMERICAL METHODS IN BIOMEDICINE</b>		
<b>DEGREE: BIOMEDICAL ENGINEERING</b>	<b>YEAR: 2</b>	<b>TERM:2</b>

WEEKLY PLANNING									
WEEK	SESSION	DESCRIPTION	GROUPS (mark X)		SPECIAL ROOM FOR SESSION (Computer class room, audio-visual class room)	Indicate YES/NO If the session needs 2 teachers	WEEKLY PROGRAMMING FOR STUDENT		
			LECTURES	SEMINARS			DESCRIPTION	CLASS HOURS	HOMEWORK HOURS (Max. 7h week)
1	1	I- PRINCIPLES OF NUMERICAL MATHEMATICS. <ul style="list-style-type: none"> <li>Well-Posedness and Condition Number of a Problem</li> <li>Stability of Numerical Methods.</li> <li>Relations between Stability and Convergence.</li> <li>Sources of Error in Computational Models.</li> </ul>	X			NO	Study Sections 2.1, 2.2 and 2.4 of QSS and Chapter 3 of DCM.	1,66	6,5

1	2	Review of the capabilities of Matlab.		X	Computer room	NO	Working with the computer. Appendix A of DCM.	1,66	
2	3	<ul style="list-style-type: none"> <li>Machine Representation of Numbers.</li> <li>The Positional System.</li> <li>The floating-Point Number System.</li> <li>Distribution of Floating-Point Number in Its Machine Representation.</li> <li>Machine Floating-Point Operations.</li> </ul>	X			NO	Study Section 2.5 of QSS and Chapter 3 of DCM.	1,66	6,5
2	4	Taylor Series. Keeping Errors Small. The IEEE standard for floating-point representation. Roundoff error accumulation and cancellation error.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Chapter 3 of DCM.	1,66	
3	5	<p>II- ROOTFINDING OF NONLINEAR EQUATIONS.</p> <ul style="list-style-type: none"> <li>Conditioning of a Nonlinear Equation.</li> <li>The Newton-Raphson Method.</li> <li>Newton's Methods for Simultaneous Nonlinear Equations.</li> </ul>	X			NO	Study Sections 6.1 and 6.2 of QSS. Section 5.6 of DCM.	1,66	
3	6	Full implementation of Newton-Raphson Method for a nonlinear equation. Plot the trajectory to the root. Two-Dimensional Graphics. Multiple Plots in a Figure.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Chapter 5 of DCM and Section 8.1 of HH.	1,66	6,5
4	7	<p>III- UNCONSTRAINED OPTIMIZATION.</p> <ul style="list-style-type: none"> <li>Necessary and Sufficient conditions for Optimality. Convexity.</li> <li>Basis Concepts: Starting Design, Direction Vector, and Step Size.</li> </ul>	X			NO	Study Sections 7.2.1 and 7.2.2 of QSS and Chapter 3 of BC.	1,66	6,5

		<ul style="list-style-type: none"> <li>The Steepest Descent Methods.</li> </ul>							
4	8	Three-Dimensional Graphics .Specialized Graphs for Displaying.Data . Saving and Printing.		X	Compu ter room	NO	Working with the computer. Applying sentences of Sections 8.2, 8.3 and 8.4 of HH.	1,66	
5	9	<ul style="list-style-type: none"> <li>The Conjugate Gradient Methods.</li> <li>Newton's Methods.</li> </ul>	X			NO	Study Sections 7.2.4 and 7.2.5 of QSS and Chapter 3 of BC.	1,66	
5	10	Implementation of Newton, Conjugate Directions FR or PR Algorithms, pros and cons.		X	Compu ter room	NO	Working with the computer. Applying algorithms of Chapters 3 and 4 of [FJNT]	1,66	6,5
6	11	<ul style="list-style-type: none"> <li>Quasi-Newton Methods.</li> <li>Approximate Line Search.</li> </ul>	X			NO	Study Sections 7.2.7 and 7.2.3 of QSS. Chapter 3 of BC.	1,66	
6	12	Implementation of Broyden Method, DFP and BFGS Algorithms, pros and cons.		X	Compu ter room	NO	Working with the computer. Applying algorithms of Chapters 3 and 5 of [FJNT].	1,66	6,5
7	13	<p>IV- FINITE DIFFERENCE METHODS: INTERPOLATION, DIFFERENTIATION AND INTEGRATION.</p> <ul style="list-style-type: none"> <li>Backward, Forward, and Central Differences.</li> <li>Interpolating Polynomials.</li> <li>The interpolation Error.</li> <li>Interpolating of Equally Spaced Points</li> </ul>	X			NO	Study Sections 8.1 and 8.2 of QSS. Sections 6.3, 6.4, 6.5 and 6.7 of DCM.	1,66	
7	14	Perform function of Gregory-Newton method for interpolation of equally spaced data.		X	Compu ter room	NO	Working with the computer. Solve Numerical Examples of Section 6.7 of DCM.	1,66	6,5
8	15	<ul style="list-style-type: none"> <li>Interpolation of Unequally Spaced Points</li> <li>Lagrange interpolation.</li> </ul>	X			NO	Study Sections 8.3 and 8.6 of QSS. Section 6.8 of DCM.	1,66	6,5

		<ul style="list-style-type: none"> <li>Spline interpolation.</li> </ul>							
8	16	Interpolation of Runge's function using cubic splines.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Section 8.6.1 of QSS.	1,66	
9	17	<ul style="list-style-type: none"> <li>Integration Formulas.</li> <li>Newton-Cotes Formulae.</li> <li>Richardson Extrapolation.</li> <li>Romberg Integration.</li> </ul>	X			NO	Study Sections 9.1, 9.2 and 9.6 of QSS.  Sections 6.9, 6.10 of DCM.	1,66	
9	18	Implementation of Composite Trapezoidal, Closed Newton-Cotes Formula and Romberg Integration.		X	Computer room	NO	Working with the computer. Applying programs of Sections 9.2, 9.3, 9.4, 9.5 and 9.6 of QSS.	1,66	6,5
10	19	<p>V- NUMERICAL SOLUTIONS OF ORDINARY DIFFERENTIAL EQUATIONS.</p> <ul style="list-style-type: none"> <li>ODEs and Lipschitz Condition.</li> <li>One Step Numerical Methods.</li> </ul> <p>Zero-Stability, Convergence Analysis and Absolute Stability.</p>	X			NO	Study Sections 11.1, 11.2 and 11.3 of QSS.	1,66	
10	20	Implementation of One-Step Methods.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Chapter 7 of DCM. Plotting stability regions.	1,66	6,5
11	21	<ul style="list-style-type: none"> <li>Multistep Methods</li> </ul> <ol style="list-style-type: none"> <li>Adams Method.</li> <li>BDF Methods.</li> <li>Consistency.</li> </ol> <p>The root condition.</p>	X			NO	Study Sections 11.5 and 11.6 of QSS.	1,66	
11	22	Implementation of Multi-Step Methods.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Chapter 7 of DCM. Plotting stability regions.	1,66	6,5

12	23	4- Stability and Convergence. 5- Absolute Stability. Predictor-Corrector Methods.	X				Study	1,66	
12	24	Implementation of Predictor-Corrector Scheme.		X	Computer room	NO	Working with the computer. Applying Matlab program of Section 11.7 of QSS.	1,66	6,5
13	25	<ul style="list-style-type: none"> <li>Runge Kutta Methods.</li> <li>1- Derivation of an Explicit RK.</li> <li>2- Stepsize Adaptivity for RK.</li> <li>3- Implicit RK.</li> <li>4- Regions of Absolute Stability</li> <li>5- Systems of ODEs.</li> <li>6- Stiff Problems.</li> </ul>	X			NO	Study Sections 11.9 and 11.10 of QSS.	1,66	
13	26	Implementation of Runge-Kutta Methods.		X	Computer room	NO	Working with the computer. Solve Numerical Examples of Chapter 7 of DCM.	1,66	6,5
14	27	VI- APROXIMATION THEORY. <ul style="list-style-type: none"> <li>Fourier Transform.</li> </ul>	X			NO	Study Section 10.7, 10.8 and 10.9 of QSS.	1,66	
14	28	Implementation of FFT.		X	Computer room	NO	Working with the computer. Applying Matlab programs of Section 10.9 of QSS.	1,66	6,5
	29	Review and tutoring.	X			NO		1,66	
<b>Subtotal 1</b>								<b>48,14</b>	<b>91</b>
<b>Total 1 (Hours of class plus student homework hours between weeks 1-14)</b>								<b>139,14</b>	

15		Tutorials, handing in, etc				NO		2	6
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16									
17		Assessment				NO			3
18									6
								<b>Subtotal 2</b>	<b>5</b>
									<b>12</b>
								<b>Total 2 (Hours of class plus student homework hours between weeks 15-18)</b>	
								17	
								<b>TOTAL (Total 1 + Total 2)</b>	
								<b>156.14</b>	

[BC] A. Belegundu and T. Chandrupatla: “Optimization Concepts and Applications in Engineering”, Cambridge University Press, **Second Edition**. 2011.

[DCM] S. Dunn, A. Constantinides and P. Moghe: “Numerical Methods in Biomedical Engineering”, 2010.

[FJNT] P.E. Frandsen, K. Jonasson, H.B. Nielsen, O. Tingleff: "Unconstrained Optimization", IMM, DTU. 1999.

[HH] D. Higham and N. Higham: “Matlab Guide”, SIAM, Second Edition. 2005.

[K] C. Kelley: “Iterative Methods for Optimization”, SIAM, 1999.

[QSS] A. Quarteroni, R. Sacco and F. Saleri: “Numerical Mathematics”, Springer. 2007.

[DH] P. Deufhard and A. Hohmann : “Introduction to Scientific Computing”, Second Edition, Springer. 2002.

[DB] P. Deufhard and Bornemann : “Scientific Computing with Ordinary Differential Equations”, Springer. 2001.

