

Academic Year: ( 2023 / 2024 )

Review date: 28-04-2023

Department assigned to the subject: Bioengineering Department

Coordinating teacher: PASCAU GONZALEZ GARZON, JAVIER

Type: Electives ECTS Credits : 3.0

Year : 4 Semester : 1

**REQUIREMENTS (SUBJECTS THAT ARE ASSUMED TO BE KNOWN)**

Computer vision

**OBJECTIVES**

The objective of this course is to provide students with a broad perspective on robotic concepts and technologies applied to (and inspired by) biomedical research and practice.

**DESCRIPTION OF CONTENTS: PROGRAMME**

- 1 Introduction
- 2 Robots for biomedical research
- 3 Surgery robotics, teleoperation, cooperative manipulation
- 5 Robotics prosthetics
- 6 Neuro-rehabilitation robotics
- 7 Medical imaging
- 8 Biomimetic robotics

**LEARNING ACTIVITIES AND METHODOLOGY****THEORETICAL PRACTICAL CLASSES.**

Knowledge and concepts students must acquire. Receive course notes and will have basic reference texts. Students partake in exercises to resolve practical problems.

**TUTORING SESSIONS.**

Individualized attendance (individual tutoring) or in-group (group tutoring) for students with a teacher. Subjects with 6 credits have 4 hours of tutoring/ 100% on- site attendance.

**STUDENT INDIVIDUAL WORK OR GROUP WORK.**

Subjects with 6 credits have 98 hours/0% on-site.

**WORKSHOPS AND LABORATORY SESSIONS.**

Subjects with 3 credits have 4 hours with 100% on-site instruction. Subjects with 6 credits have 8 hours/100% on-site instruction.

**ASSESSMENT SYSTEM****FINAL EXAM.**

Global assessment of knowledge, skills and capacities acquired throughout the course. The percentage of the evaluation varies for each subject between 60% and 0%.

**CONTINUOUS EVALUATION.**

Assesses papers, projects, class presentations, debates, exercises, internships and workshops throughout the course. The percentage of the evaluation varies for each subject between 40% and 100% of the final grade.

**% end-of-term-examination:** 60

**% of continuous assessment (assignments, laboratory, practicals...):** 40

**BASIC BIBLIOGRAPHY**

- J. P. Desai, S. Agrawal, A. Ferreira, R. V. Patel (Editors) The Encyclopedia of Medical Robotics 4 Volumes., World Scientific., 2019

