Technologies for Autonomous and Unmanned Systems

Academic Year: (2023 / 2024)

Department assigned to the subject: Signal and Communications Theory Department

Coordinating teacher: GONZALEZ SERRANO, FRANCISCO JAVIER

Type: Electives ECTS Credits : 3.0

Year : Semester :

REQUIREMENTS (SUBJECTS THAT ARE ASSUMED TO BE KNOWN)

Digital Communications Communication Channels and Systems Electronic Systems

OBJECTIVES

- Know the basic structure of unmanned vehicles.
- Know the typical architecture of the on-board and ground systems, as well as their fundamental components.
- Design the architecture of the systems needed for the fulfillment of a specific mission.

DESCRIPTION OF CONTENTS: PROGRAMME

Unit 1. Introduction to RPAS / UAS (ES)

- History
- Elements: operating environment, air and ground segments; payload; support and maintenance
- Vehicle types and classification
- Applications: missions
- Regulations: operation
- Socio-economic impact
- Unit 2. Technologies
- Propulsion
- * Electric: Brushless motors, Electronic Speed Controllers (ESC)
- * Others: piston, turbofan, ...
- * Propellers
- Electric power)
- * Batteries, Fuel Cells. Systems based on applied electrical energy, internal circuits of drones
- * Converters (BEC)
- Unit 3. Communications + Ground Segment: Ground Control Station

Communication

- * Command and Control: RC Controller / Receiver
- * Telemetry
- * Data links: connectivity
- Unit 4. Drone Fundamentals
- Configurations: 2/3/4/6/8-copter
- Basic flight maneuvers
- * Performances
- Guidance and control (Flight Control System)
- * Autopilots. IMU. GPS
- * Control software: mission planner
- Unit 5. Design methodologies: Systems Engineering
- * V & V: CONOPS, Requirements, Design, Testing
- Design and manufacturing
- * Materials
- * Design software
- * 3D Printing
- Unit 6. Payload (onboard)
- * Sensed
- Optical (Visible, IR), RADAR, LiDAR, SONAR, Ultrasound
- * Actuators: gimbals, etc
- GCS + Processing (onground)

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* Detection, classification, monitoring. Data Fusion.

* Information processing and analysis software

Practice 1: Drone Architecture and Components

Practice 2: Communications

- Practice 3: Flight Control
- Practice 4: Payload printing
- Practice 5: Software Development
- Practice 6: Calculation of airplanes:
- Configuration software: eCalc
- Race Drone vs surveillance Drone exercise

Practice 7: GCS and application design

- Practice 8: Flight and Testing
- Plan mission + mission planner

LEARNING ACTIVITIES AND METHODOLOGY

Theory Classes: 0.75 ECTS Practical/Lab. classes: 0.5 ECTS Group Project: 1 ECTS - Development of a project of systems integration in a UAV Individual Project: 0.75 ECTS The learning activities, methodology and tutoring regime will be organized according to the regulations specified by the university: https://www.uc3m.es/ss/Satellite/UC3MInstitucional/es/ListadoNormativas/1371206706530/Estudios_de_Grado

ASSESSMENT SYSTEM

End-of-term exam: 50 % - The minimum passing score is 4 out of 10 points. Group Project: 50 %

Class attendace (both Lectures and Laboratory) is mandatory in orden to pass the subject.

% end-of-term-examination:	50
% of continuous assessment (assigments, laboratory, practicals):	50

BASIC BIBLIOGRAPHY

- James Aber Irene Marzolff Johannes Ries Susan Aber Small-Format Aerial Photography and UAS Imagery, Academic Press. 2nd Edition., 2019

- Paul Gerin Fahlstrom Introduction to UAV Systems, John Wiley & Sons; 4th Edition, 2012
- Plamen Angelov Sense and Avoid in UAS, Wiley-Blackwell, 2012

- Reg Austin Unmanned Aircraft Systems: UAVS Design, Development and Deployment, Wiley-Blackwell; Edición: 1, 2010

ADDITIONAL BIBLIOGRAPHY

- Brent Terwilliger, David C. Ison, John Robbins Small Unmanned Aircraft Systems Guide: Exploring Designs,

Operations, Regulations, and Economics, Aviation Supplies & Academics, Inc., 2017

- Douglas M. Marshall, Richard K. Barnhart, Eric Shappee, Michael Thomas Most Introduction to Unmanned Aircraft Systems, CRC Press, 2016