## Collaborative Robots

Department assigned to the subject: Systems Engineering and Automation Department
Coordinating teacher:
Type: Compulsory ECTS Credits : 3.0
Year : 4 Semester : 1

## DESCRIPTION OF CONTENTS: PROGRAMME

1. Introduction to Cobots
2. Physical human-robot collaboration (space sharing, master-slave architectures, sensors, control systems, etc.)
3. Safety in industrial installation with Cobots (levels, exclusions, calibration, etc.)
4. Robots design for collaborate (features, force/torque control, hybrid control, axis decoupling, etc.)
5. Collaborative robot programming (LBR iiwa)
6. Criteria for the implementation of collaborative robotic systems (lay-ours ¿ design, space separation and shearing, etc.)
7. Examples of success stories and trends

## LEARNING ACTIVITIES AND METHODOLOGY

THEORETICAL PRACTICAL CLASSES.
Knowledge and concepts students must acquire. Receive course notes and will have basic reference texts. Students partake in exercises to resolve practical problems.

TUTORING SESSIONS.
Individualized attendance (individual tutoring) or in-group (group tutoring) for students with a teacher. Subjects with 6 credits have 4 hours of tutoring/ 100\% on- site attendance.

STUDENT INDIVIDUAL WORK OR GROUP WORK.
Subjects with 6 credits have 98 hours/0\% on-site.
WORKSHOPS AND LABORATORY SESSIONS.
Subjects with 3 credits have 4 hours with 100\% on-site instruction. Subjects with 6 credits have 8 hours/100\% on-site instruction.

## ASSESSMENT SYSTEM

FINAL EXAM.
Global assessment of knowledge, skills and capacities acquired throughout the course. The percentage of the evaluation varies for each subject between $60 \%$ and $0 \%$.

CONTINUOUS EVALUATION.
Assesses papers, projects, class presentations, debates, exercises, internships and workshops throughout the course. The percentage of the evaluation varies for each subject between $40 \%$ and $100 \%$ of the final grade.
\% end-of-term-examination: 60
\% of continuous assessment (assigments, laboratory, practicals...): 40

