Machine Mechanics

Academic Year: (2019 / 2020) **Review date: 27-11-2019**

Department assigned to the subject: Mechanical Engineering Department

Coordinating teacher: MENESES ALONSO, JESUS

Type: Compulsory ECTS Credits : 6.0

Year : 3 Semester : 1

REQUIREMENTS (SUBJECTS THAT ARE ASSUMED TO BE KNOWN)

Physics I
Calculus I
Calculus II
Linear algebra

OBJECTIVES

By the end of this subject, students will be able to have:
1. The knowledge and understanding of the fundamentals of kinematic and dynamic of the rigid body and machines theory and mechanisms.
2. The ability to apply their knowledge and understanding to identify, formulate and solve problems of kinematics and dynamics of the rigid solid and mechanisms and simple machines using established methods.
3. The ability to design and perform experiments on machine theory and mechanisms, analyse the data and draw conclusions.
4. The technical and laboratory skills in machine theory and mechanisms.
5. The ability to select and use appropriate equipment, tools and methods to solve problems of kinematics and dynamics of rhe rigid body, mechanisms and simple machines.
6. The ability to combine theory and practice to solve problems of kinematics and dynamics of rigid body, mechanisms and simple machines
7. The understanding of methods and techniques applicable in machine theory and mechanisms and their limitations.

DESCRIPTION OF CONTENTS: PROGRAMME

1. Introduction to Mechanics. Static. Kinematics of the point. Systems of Units
   1.1. Mechanics
   1.2. Basics
   1.3. The particle and rigid body
   1.4. Static
   1.5. Point Kinematics
   1.6. Speed Concept
   1.7. Acceleration Concept
   1.8. System Units

2. Kinematics of rigid bodies
   2.1. Orthonormal basis of a scalar dependent
   2.2. Movement of the Rigid Solid
   2.3. Instantaneous axis of rotation
   2.4. Intrinsic component of acceleration
   2.5. Acceleration of Rigid Solid
   2.6. Movement Absolute, Relative and Drag
   2.7. Speed relative motion
   2.8. Acceleration in relative motion
   2.9. Euler Angles

3. Dynamics of rigid
   3.1. Newton's Laws
   3.2. No Inertial Reference Systems
   3.3. Inertia Forces
   3.4. Momentum

3.5. Angular momentum
3.6. Theorem of angular momentum
3.7. Motion of a rigid body with a fixed point
3.8. Gyroscopic motion
3.9. Motion of a rigid body with a fixed axis
3.10. Equation of Motion
3.11. Calculation of reactions
3.12. Balancing of shafts

4. Energy and Power
4.1. Work and power
4.2. Kinetic energy. Theorem of the prime movers
4.3. Potential energy
4.4. Energy Conservation
4.5. Friction Forces
4.6. Mechanical Performance

5. Mechanisms Plans
5.1. Introduction
5.2. Component parts of a mechanism
5.3. Mobility mechanisms
5.4. Four-bar linkage
5.5. Determining the relative CIR

6. Kinematics of Mechanisms Plans
6.1. Determination of rates members of a mechanism
6.2. Determination of members of an acceleration mechanism
6.3. Value of accelerations and velocities of points of kinematic pairs
6.4. Cinema speed
6.5. Cinema accelerations.

7. Dynamics of Mechanisms Plans
7.1. Introduction
7.2. Kinetic analysis of mechanisms-static flat
7.3. Static Analysis
7.4. Analysis Efforts Inertia
7.5. Full Dynamic Analysis

LEARNING ACTIVITIES AND METHODOLOGY

Master class, classroom exercises and / or laboratories and work.

ASSESSMENT SYSTEM

The subject will be evaluated according to the following criteria:

¿ Continuous evaluation of the first part of the subject (EC1): Up to 1,5 points
¿ Continuous evaluation of the second part of the subject (EC2): Up to 1,5 points
¿ Laboratories (P): Up to 1 point

Ordinary final call
Ordinary Final Exam, with two parts: Up to 6 points
¿ Final exam of the first part of the subject (EF1): Up to 3 points
¿ Final exam of the second part of the subject (EF2): Up to 3 points
Total: Up to 10 points

To pass it is necessary to obtain a minimum of 3,5 points out of 10 in the total final exam

% end-of-term-examination:	60
% of continuous assessment (assigments, laboratory, practicals…):	40

BASIC BIBLIOGRAPHY

- Erdman, A., Mechanism design . Vol I : Analysis and synthesis, Prentice Hall, New Jersey, 2001

- Hibbeler, R.C., Engineering Mechanics. Dynamics, Prentice Hall, Singapore, 2010

- J.C. García-Prada, C. Castejón, H. Rubio, J. Meneses Problemas resueltos de Teoría de Máquinas y

Mecanismos 2ed, Thomson-Paraninfo, , 2014

- M. Artés Mecánica, Universidad Nacional de Educación a Distancia, 2003
- Norton, R.L, Design of machinery, McGraw-Hill, New York, 2012
- Uicker, J., Theory of machines and mechanisms, Oxford University Press, New York, 2010

ADDITIONAL BIBLIOGRAPHY

- A. Lamadrid, A. Corral Cinemática y dinámica de máquinas, E.T.S.I.I. Madrid, 1969.